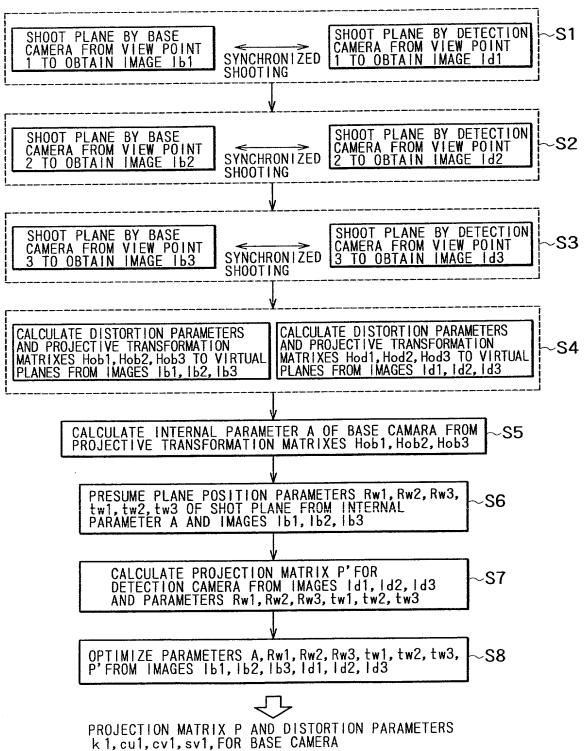


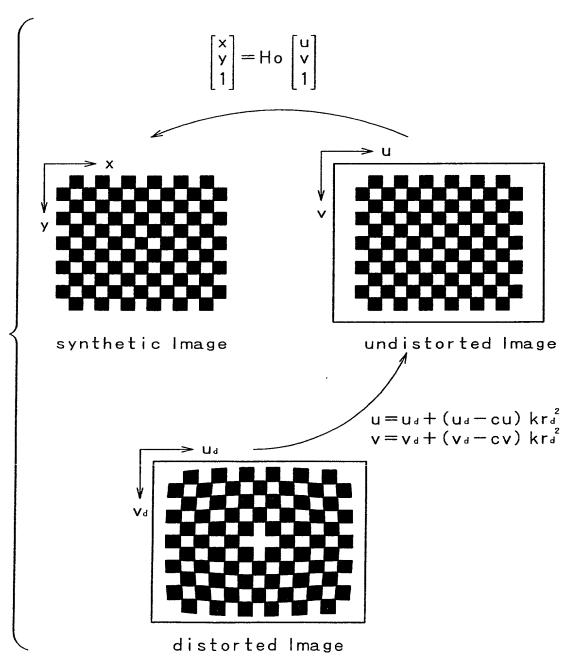
FIG.2

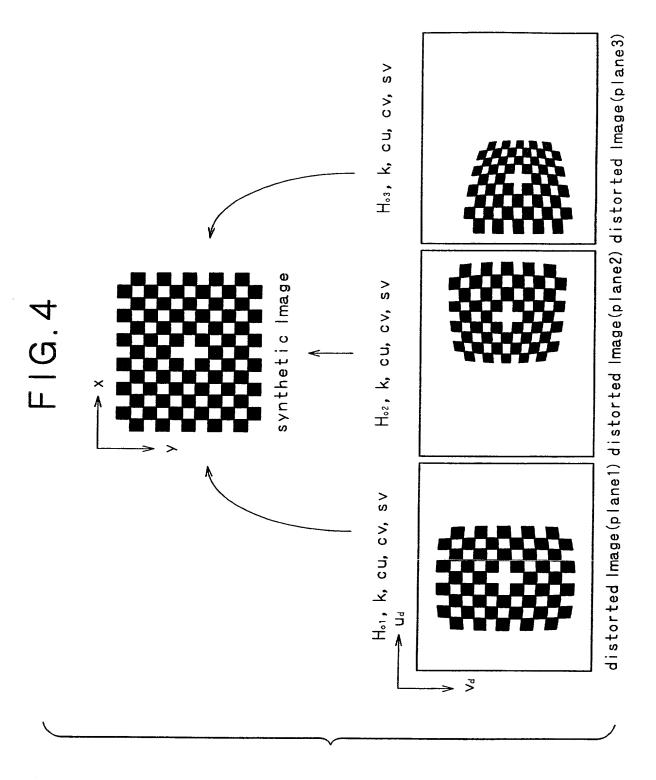


k 1, cu1, cv1, sv1, FOR BASE CAMERA

PROJECTION MATRIX P'AND DISTORTION PARAMETERS
k 2, cu2, cv2, sv2, FOR DETECTION CAMERA

FIG.3





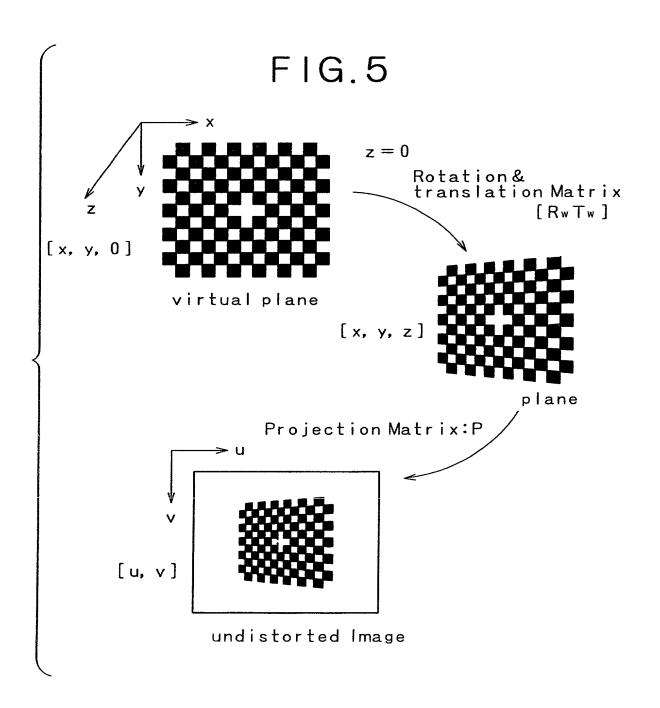
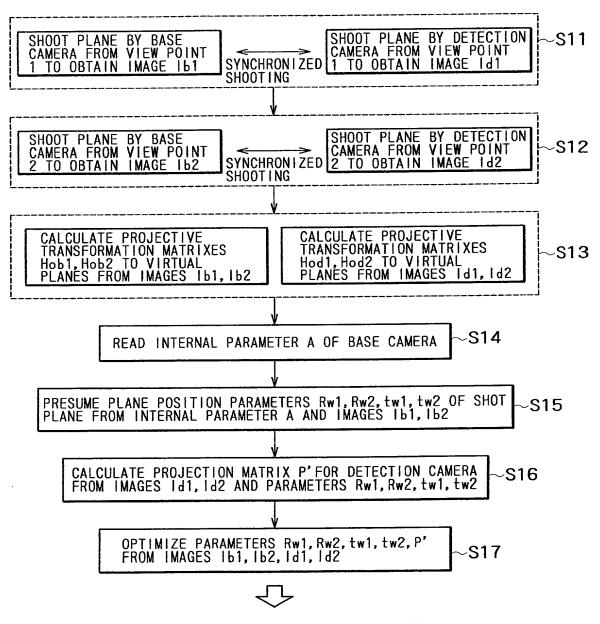


FIG.6



PROJECTION MATRIX P'FOR DETECTION CAMERA

